1. A method of monitoring a substrate having a metal layer during chemical mechanical polishing, the method comprising:

polishing a metal layer of a substrate with a polishing pad;

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sweeping a sensor along a path across the substrate during the polishing step;

generating a sequence of sensor measurements from the sensor as the sensor sweeps along the path;

associating each of the sensor measurements with a radial position on the substrate; dividing the sensor measurements into a plurality of radial ranges based on the radial positions; and

determining a characteristic of the metal layer for each radial range from the measurements associated with that radial range.

- 2. The method of claim 1, wherein polishing includes supporting the polishing pad on a support and moving the support relative to substrate.
- 3. The method of claim 2, wherein the sensor is secured to the support so that moving the support relative to the substrate causes the sensor to sweep along the path.
- 4. The method of claim 3, wherein the support comprises a platen and moving the support includes rotating the platen.
 - 5. The method of claim 1, wherein generating a sequence of sensor measurements includes directing a light beam from the sensor to the substrate.
- 6. The method of claim 5, wherein generating a sequence of sensor measurements includes receiving a reflection of the light beam from the substrate to the sensor.
 - 7. The method of claim 1, further comprising detecting a polishing endpoint using measurements from at least one of the radial ranges.
 - 8. The method of claim 7, further comprising stopping chemical mechanical polishing when the endpoint is identified.

9. The method of claim 7, wherein detecting the polishing endpoint includes identifying a predetermined pattern from the measurements.

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- 10. The method of claim 9, wherein the identifying step comprises comparing the measurements to a predetermined threshold.
- 11. The method of claim 9, wherein the sensor makes a plurality of sweeps across the substrate to generate a series of measurements.

12. The method of claim 11, wherein the identifying step comprises determining whether a series of measurements from the sensor have a downward trend.

- 13. The method of claim 11, wherein the identifying step comprises determining whether a series of measurements from the sensor have an upward trend.
- 14. The method of claim 11, wherein the identifying step comprises determining whether a series of measurements from the sensor have a flat trend.
- 15. The method of claim 1, wherein the associating step includes determining a time that the sensor crosses a midline of the substrate, and determining a position of the sensor at a measurement time from a difference between the measurement time and the time that the sensor crosses the midline of the substrate.
 - 16. The method of claim 15, wherein the associating step includes determining a position of the carrier head from a carrier head sweep profile.
 - 17. An apparatus for polishing a metal layer of a substrate, comprising: a support to hold a polishing pad;
 - a carrier head to hold the substrate in contact with a surface of the substrate;

a motor coupled to the support to cause relative motion between the substrate and the polishing pad;

a sensor secured to the support to generate a sequence of sensor measurements as the sensor sweeps along a path; and

a computer configured to associate each of the sensor measurements with a radial position on the substrate, divide the sensor measurements into a plurality of radial ranges based on the radial positions, and determine a characteristic of the metal layer for each radial range from the measurements associated with that radial range.

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- 18. The apparatus of claim 17, wherein the sensor includes a light source to generate a light beam directed to the substrate and a detector to detect a reflection of the light beam from the substrate.
 - 19. The apparatus of claim 17, wherein the support comprises a rotatable platen.
- The apparatus of claim 17, wherein the computer is configured to stop chemical mechanical polishing when an endpoint is identified.